

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
		<p>input\$6 adj device and apply\$6 same repeat\$6 same comput\$6 same amount same external same force)</p> <p>force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6 and control\$6 and section and computing and operation and amounts and operation and directions and operation and section and based and position and signal and controlling and drive and actuator and operation and section and operated and direction and position and external same force same increases and direction same opposite and operation and direction and operation and section and until and operation and amount and operation and section and reaches and predetermined and operation and section and reaches and operation and section and predetermined and external and force and predetermined and operation and amount and reached and applied and direction and opposite and operation and direction and operation and section and and operation and section and stopped and external and force and applied and operation and section and reduced and increase and returning and amount</p>	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 09:01

EAST Search History

		force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6 and control\$6 and section and computing and operation and amounts and operation and directions and operation and section and based and position and signal and controlling and drive and actuator and operation and section and operated and direction and position and external same force same increases and direction same opposite and operation and direction and operation and section and until and operation and amount and operation and section and reaches and predetermined and operation and amount and operation and amount and operation and section and reaches and predetermined and operation and amount and external and force and corresponding and predetermined and operation and amount and reached and applied and direction and opposite and operation and direction and operation and section and and operation and section and stopped and external and force and applied and operation and section and reduced and increase and returning and amount and operation and section and stopping and position and operation and section	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 10:08
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EAST Search History

		force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6 and position\$6 same sensor and control\$6 and section and computing and operation and amounts and operation and directions and operation and section and based and position and signal and controlling and drive and actuator and operation and section and operated and direction and start and position and external same force same increases and direction same opposite and operation and direction and operation and section and until and operation and amount and operation and section and reaches and predetermined and operation and amount and operation and amount and operation and section and reaches and predetermined and operation and amount and external and force and corresponding and predetermined and operation and amount and reached and applied and direction and opposite and operation and direction and operation and section and and operation and section and stopped and external and force and applied and operation and section and reduced and increase and returning and amount and operation and section and stopping and position and operation and section	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 10:04
L1	2983534	input adj device and external dj force\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 14:06
L2	1556	input adj device and external adj force\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 14:07
L3	2	input adj device and (external adj force\$6) and (repeat\$6 adj comput\$6)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 14:08

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L4	8	Matsumoto same Ken and Hayasaka same Satoshi	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 14:09
S1	228191	input adj device	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 14:06
S2	233479	input\$6 adj device\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/18 14:51
S3	39803	input\$6 adj device\$6 and force\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/18 14:51
S4	285	input\$6 adj device\$6 and force\$6 adj apply\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 13:49
S5	62	input\$6 adj device\$6 and force\$6 adj apply\$6 and joystick\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/18 14:52
S6	47	input\$6 adj device\$6 and force\$6 adj apply\$6 and joystick\$6 and actuat\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/18 14:52
S7	32	input\$6 adj device\$6 and force\$6 adj apply\$6 and joystick\$6 and actuat\$6 and position\$6 adj sensor	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 15:10
S8	11	input\$6 adj device\$6 and force\$6 adj apply\$6 and joystick\$6 and actuat\$6 and position\$6 adj sensor and external	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/18 15:14
S9	12	input\$6 adj device\$6 and force\$6 adj apply\$6 and joystick\$6 and actuat\$6 and position\$6 adj sensor and external\$6 and direction\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/18 15:14

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S10	7	input\$6 adj device\$6 and force\$6 adj apply\$6 and joystick\$6 and actuat\$6 and position\$6 adj sensor and external\$6 and direction\$6 same chang\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/18 15:31
S11	124	700/85.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/18 15:16
S12	58	700/85.ccls. and force\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/18 15:16
S14	4	700/85.ccls. and force\$6 same apply\$6 same input\$6 same device\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/18 15:17
S15	2234	ken and matsumoto	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/18 15:26
S16	87	ken and matsumoto and input adj device	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/18 15:27
S17	6	ken and matsumoto and input adj device and apply\$6 adj force\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/18 15:30
S18	4	ken and matsumoto and input adj device and apply\$6 adj force\$6 and satoshi and hayasaka	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/18 15:31
S19	2	input\$6 adj device\$6 and force\$6 adj apply\$6 and joystick\$6 and actuat\$6 and position\$6 adj sensor and external\$6 and direction\$6 same chang\$6 and opposit\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/18 16:39

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S20	1	input\$6 adj device\$6 and force\$6 adj apply\$6 and joystick\$6 and actuat\$6 and position\$6 adj sensor and external\$6 same force\$6 same apply\$6 same direction\$6 same opposit\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/18 16:40
S21	4	input\$6 adj device\$6 and actuat\$6 and position\$6 adj sensor and external\$6 same force\$6 same apply\$6 same direction\$6 same opposit\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/18 16:40
S22	0	forc same applying same input same device and position same sensor same detecting	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/18 16:48
S23	102	force same applying same input same device and position same sensor same detecting	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/18 16:48
S24	8	force same applying same input same device and position same sensor same detecting and actuator same applying same external same force	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/18 16:51
S25	16	700/85.ccls. and force\$6 same apply\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 08:53
S26	0	"20020108802" and joystick	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 09:46
S27	1	force same applying same input same device and position same sensor same detecting and actuator same applying same external same force and control same section and controlling same drive same actuator same based same position\$6 same signal\$6 same output\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 09:54

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S28	2	force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 11:02
S29	1	force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6 and position\$6 same sensor and control\$6 and section and computing and operation and amounts and operation and directions and operation and section and based and position and signal and controlling and drive and actuator and operation and section and operated and direction and start and position	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 10:04
S30	1	force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6 and position\$6 same sensor and control\$6 and section and computing and operation and amounts and operation and directions and operation and section and based and position and signal and controlling and drive and actuator and operation and section and operated and direction and position	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 10:05
S31	1	force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6 and position\$6 same sensor and control\$6 and section and computing and operation and amounts and operation and directions	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 10:07

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S32	1	force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6 and control\$6 and section and computing and operation and amounts and operation and directions and operation	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 10:07
S33	1	force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6 and control\$6 and section and computing and operation and amounts and operation and directions and operation and section and based and position and signal and controlling and drive and actuator and operation and section	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 10:08
S34	1	force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6 and control\$6 and section and computing and operation and amounts and operation and directions and operation and section and based and position and signal and controlling and drive and actuator and operation and section and operated and direction and position and external same force same increases and direction same opposite and operation	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 10:09

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S35	1	force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6 and control\$6 and section and computing and operation and amounts and operation and directions and operation and section and based and position and signal and controlling and drive and actuator and operation and section and operated and direction and position and external same force same increases and direction same opposite and operation and direction and operation and section and until and operation and amount and operation and section and reaches	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 10:09
S36	0	force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6 and control\$6 and section and computing and operation and amounts and operation and directions and operation and section and based and position and signal and controlling and drive and actuator and operation and section and operated and direction and position and external same force same increases and direction same opposite and operation and direction and operation and section and until and operation and amount and operation and section and reaches and predetermined and operation and amount and operation and amount and operation and section and reaches and predetermined and operation and amount and external and force and corresponding	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 10:11

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S37	0	force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6 and control\$6 and section and computing and operation and amounts and operation and directions and operation and section and based and position and signal and controlling and drive and actuator and operation and section and operated and direction and position and external same force same increases and direction same opposite and operation and direction and operation and section and until and operation and amount and operation and section and reaches and predetermined and operation and section and reaches and predetermined and operation and amount and external and force and corresponding	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 10:11
S38	0	force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6 and control\$6 and section and computing and operation and amounts and operation and directions and operation and section and based and position and signal and controlling and drive and actuator and operation and section and operated and direction and position and external same force same increases and direction same opposite and operation and direction and operation and section and until and operation and amount and operation and section and reaches and predetermined and operation and section and reaches and predetermined and external and force and corresponding	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 10:12

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S39	1673574	force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6 and control\$6 and section and computing and operation and amounts and operation and directions and operation and section and based and position and signal and controlling and drive and actuator and operation and section and operated and direction and position and external same force same increases and direction same opposite and operation and direction and operation and section and until and operation and amount and operation and section and reaches and predetermined and operation and section and reaches operation and section	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 10:12
S40	1	force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6 and control\$6 and section and computing and operation and amounts and operation and directions and operation and section and based and position and signal and controlling and drive and actuator and operation and section and operated and direction and position and external same force same increases and direction same opposite and operation and direction and operation and section and until and operation and amount and operation and section and reaches and predetermined and operation and section and reaches and operation and section	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 10:13

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S41	0	force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6 and control\$6 and section and computing and operation and amounts and operation and directions and operation and section and based and position and signal and controlling and drive and actuator and operation and section and operated and direction and position and external same force same increases and direction same opposite and operation and direction and operation and section and until and operation and amount and operation and section and reaches and predetermined and operation and section and reaches and operation and section and predetermined and external and force and corresponding	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 10:14
S42	1	force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6 and control\$6 and section and computing and operation and amounts and operation and directions and operation and section and based and position and signal and controlling and drive and actuator and operation and section and operated and direction and position and external same force same increases and direction same opposite and operation and direction and operation and section and until and operation and amount and operation and section and reaches and predetermined and operation and section and reaches and operation and section	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 10:14

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S43	0	force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6 and control\$6 and section and computing and operation and amounts and operation and directions and operation and section and based and position and signal and controlling and drive and actuator and operation and section and operated and direction and position and external same force same increases and direction same opposite and operation and direction and operation and section and until and operation and amount and operation and section and reaches and predetermined and operation and section and reaches and operation and section and predetermined and external and force and correspond\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 10:14
S44	1	force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6 and control\$6 and section and computing and operation and amounts and operation and directions and operation and section and based and position and signal and controlling and drive and actuator and operation and section and operated and direction and position and external same force same increases and direction same opposite and operation and direction and operation and section and until and operation and amount and operation and section and reaches and predetermined and operation and section and reaches and operation and section and predetermined and external and force	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 10:15

EAST Search History

S45	1	force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6 and control\$6 and section and computing and operation and amounts and operation and directions and operation and section and based and position and signal and controlling and drive and actuator and operation and section and operated and direction and position and external same force same increases and direction same opposite and operation and direction and operation and section and until and operation and amount and operation and section and reaches and predetermined and operation and section and reaches and operation and section and predetermined and external and force and predetermined and operation and amount and reached and applied and direction and opposite and operation and direction and operation and section and operation and section and stopped and external and force and applied and operation and section and reduced and increase and returning and amount	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 10:16
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EAST Search History

S46	1	force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6 and control\$6 and section and computing and operation and amounts and operation and directions and operation and section and based and position and signal and controlling and drive and actuator and operation and section and operated and direction and position and external same force same increases and direction same opposite and operation and direction and operation and section and until and operation and amount and operation and section and reaches and predetermined and operation and section and reaches and operation and section and predetermined and external and force and predetermined and operation and amount and reached and applied and direction and opposite and operation and direction and operation and section and operation and section and stopped and external and force and applied and operation and section and reduced and increase and returning and amount and operation and section and stopping and position	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 10:16
S47	2	"6,987,508".pn.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 10:52
S48	1	"6,987,508".pn. and force\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 10:53
S49	1	"6,987,508".pn. and force\$6 and joystick\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 10:54

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S50	1	"6,987,508".pn. and external same force\$6 and joystick\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 10:56
S51	1	"6,987,508".pn. and external same force\$6 and joystick\$6 and actuator	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 11:00
S52	0	"6,987,508".pn. and external same force\$6 and joystick\$6 and actuator and opposit\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 11:01
S53	1	"6,987,508".pn. and external same force\$6 and joystick\$6 and actuator and direct\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 15:09
S54	1	force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6 and opposit\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 11:02
S55	1	force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6 and (opposit\$6 or reverse\$6)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 11:03
S56	2	force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6 and (stop\$6 or friction\$6)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 15:09
S57	1	"6,987,508".pn. and external same force\$6 and joystick\$6 and actuator and direct\$6 and (stop\$6 or friction\$6)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 11:09

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S58	1	"6,987,508".pn. and (stop\$6 or friction\$6)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 11:09
S59	1	input\$6 adj device\$6 adj force\$6 adj apply\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 13:49
S60	1	force same applying same input same device and position same sensor and detecting and actuator same applying same external same force and control same section and controlling same drive same actuator and based same position\$6 and signal\$6 same output\$6 and (stop\$6 or friction\$6) and slop\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 15:09
S61	0	"6,987,508".pn. and external same force\$6 and joystick\$6 and actuator and direct\$6 and expo\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 15:10
S62	0	"6,987,508".pn. and external same force\$6 and joystick\$6 and actuator and direct\$6 and slop\$5	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 15:10
S63	19	input\$6 adj device\$6 and force\$6 adj apply\$6 and joystick\$6 and actuat\$6 and position\$6 adj sensor and slop\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 15:10
S64	2	input\$6 adj device\$6 and force\$6 adj apply\$6 and joystick\$6 and actuat\$6 and position\$6 adj sensor and slop\$6 and expo\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 15:11
S65	1	input\$6 adj device\$6 and force\$6 adj apply\$6 and joystick\$6 and actuat\$6 and position\$6 adj sensor and slop\$6 and exponent\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 15:22
S66	7	input\$6 adj device\$6 and force\$6 adj apply\$6 and slop\$6 and exponent\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/10/19 15:12

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S67	4	input\$6 adj device\$6 and force\$6 adj apply\$6 and joystick\$6 and slop\$6 and exponent\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 07:00
S68	0	jostick	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 07:00
S69	40633	joystick	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 07:01
S70	51	joystick and gradual and change and direction and amount and external and force and repeated and computations	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 07:04
S71	14	joystick and gradual and change and direction and amount and external and force and repeated and computations and "345"/\$.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 08:25
S72	0	joystick and gradual same change same direction same amount same external same force same repeated same computations	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 07:06
S73	0	joystick and gradual same change same direction and amount same external same force same repeated same computations	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 07:06
S74	0	joystick and gradual same change same direction and amount same external same force and repeated same computations	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 07:06
S75	0	joystick and gradual\$6 same change\$6 same direction and amount same external same force\$6 and repeat\$^ same computat\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 07:07
S76	1	joystick and gradual\$6 same change\$6 same direction and amount same external same force\$6 and repeat\$6 same computat\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 07:07

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S77	15	joystick and gradual\$6 same change\$6 and direction and amount and external and force and repeated and computations and "345"/\$.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 08:29
S78	0	joystick and gradual\$6 same change\$6 and direction and amount and external same force\$6 and repeated and computations and "345"/\$.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 08:26
S79	2	joystick and gradual\$6 same change\$6 and direction and amount and (external same force\$6 or friction same force\$6) and repeated and computations and "345"/\$.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 08:27
S80	6	joystick and gradual\$6 same change\$6 and direction and amount and (external same force\$6 or friction same force\$6) and repeated and computations	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 08:27
S81	0	joystick and gradual\$6 same change\$6 same direction and amount and external and force and repeated and computations and "345"/\$.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 08:30
S82	147	joystick and gradual\$6 same change\$6 same direction	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 08:30
S83	20	joystick and gradual\$6 same change\$6 same direction and amount and external same force	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 08:41
S84	8	joystick and gradual\$6 same change\$6 same direction and amount same external same force	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 08:35
S85	1	joystick and gradual\$6 same change\$6 same direction\$6 and amount same external same force\$6 and repeat\$6 same comput\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 08:32
S86	3	joystick and gradual\$6 same change\$6 same direct\$6 and amount same external same force\$6 and repeat\$6 same comput\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 08:32

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S87	2291762	joystick and amount same external same force same repeat\$6 smae comput\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 08:42
S88	7	joystick and amount same external same force same repeat\$6 same comput\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 08:51
S89	2	"20040167642"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 08:50
S90	26	joystick and (amount same external same force) and apply\$6 and repeat\$6 same comput\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 08:51
S91	0	joystick and (amount same external same force) and apply\$6 and repeat\$6 same comput\$6 and (maintain\$6 same direction and gradual same change\$6)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 08:53
S92	0	joystick and (amount same external same force) and apply\$6 and repeat\$6 same comput\$6 and (direction and gradual same change\$6)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 08:53
S93	26	joystick and (amount same external same force) and apply\$6 and repeat\$6 same comput\$6 and (direct\$6 and comput\$6 same change\$6)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 08:54
S94	12	joystick and (amount same external same force) and apply\$6 and repeat\$6 same comput\$6 and (comput\$6 same change\$6 same direct\$6)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 08:57
S95	19	input\$6 adj device and (amount same external same force) and apply\$6 and repeat\$6 same comput\$6 and (comput\$6 same change\$6 same direct\$6)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 08:59
S96	5	input\$6 adj device and (apply\$6 same repeat\$6 same comput\$6 same amount same external same force)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 09:01

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S97	5	input\$6 adj device and (apply\$6 same repeat\$6 same comput\$6 same amount\$6 and external same force\$6)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 09:02
S98	12	input\$6 adj device and (apply\$6 same repeat\$6 same comput\$6 same amount\$6 and force\$6)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 09:42
S99	5	input\$6 adj device and (apply\$6 same repeat\$6 same comput\$6 same amount\$6 and external same (force\$6 or pressure))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 09:03
S100	52	700/85.ccls. and input\$6 adj device	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 10:08
S101	25	700/85.ccls. and input\$6 adj device and force	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 09:59
S102	28	700/85.ccls. and joystick and force	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 09:59
S103	4	"6505088".pn.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 10:07
S104	1	"6505088".pn. and force	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 10:07
S105	1	"6505088".pn. and force and comput\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 10:07
S106	0	"6505088".pn. and force and comput\$6 and repeat\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 10:08

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S10 7	0	"6505088".pn. and force and comput\$6 and gradual	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 10:08
S10 8	60	700/85.ccls. and force\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 10:08
S10 9	31	700/85.ccls. and force\$6 same comput\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 10:09
S11 0	6	700/85.ccls. and force\$6 same comput\$6 same repeat\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 10:11
S11 1	1	700/85.ccls. and force\$6 same comput\$6 same repeat\$6 and gradual	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 10:11
S11 2	1	"6050718".pn. and repeat\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/03/14 10:23

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Application Number

IDS Flag Clearance for Application 10780986

Content	Mailroom Date	Entry Number	IDS Review	Last Modified	Reviewer
M844	2006-06-01	17	Y <input checked="" type="checkbox"/>	2006-10-18 14:38:05.0	PDharia

Day : Wednesday

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10/24/2006	40	CTNF	NON-FINAL REJECTION
06/01/2006		IDSC	INFORMATION DISCLOSURE STATEMENT CO
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